MACHINE SOLUTIONS INC.

Machine Solutions

BEAHM DESIGNS BENCH TOP DIE NECKER
MODEL 43-B

BEAHM
DESIGNS

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Welcome

Machine Solutions, Inc. (MSI) would like to take this opportunity to thank you for purchasing your new 43-B Bench Top Die Necker. At MSI, we are dedicated to bringing innovative process development solutions to both medical device and nonmedical organizations. MSI looks forward to helping your organization provide life-improving devices to your customers, today and tomorrow.

Purpose

The purpose of this document is to describe the electrical and software design of the control system for the Split Die Thermal Bonder, 43-B. This document also includes operator instructions.

Overview

The Beahm Designs Die Necker progressively reduces tubing diameter by means of a heated die. Tubing is manually drawn through the die to the desired length. The I.D. of the interchangeable dies controls the diameter of the neck tubing.

Contents

1. Benchtop Die Necker
2. Power cord

Installation

1. Place the system on a level, sturdy surface at an ergonomically viable height for the user.
2. System power is in the OFF position.
3. Connect the power cord to the main control unit.
4. Connect the air supply to the system and then to a clean, dry, and filtered compressed air source.
5. Connect the electrical umbilical to the die base unit.

Safety

Note: See Maintenance section for facilities requirements

- Place the system on a level, sturdy surface at an ergonomically viable height for the user.
- Use of eye protection when working with compressed gases and heated materials is advised.
- The maximum observed Sound Pressure Level is below 70 dB(A).
- Hot dies will become hot during operation and, depending on temperature set-point, can cause severe skin burns if contact occurs.

Caution: high voltage. Remove power and use safety precautions when servicing. Power down machine before disconnecting umbilical.

Caution: hot surface. Contact may cause burn. Allow to cool before servicing.

Caution: pinch point. Keep hands and body parts clear while in operation.

User Alerts

Do not use the equipment other than as prescribed. Examples: Do not attempt to sit on or climb on the equipment, do not place heavy objects or containers of liquid on the machine, do not to insert any foreign objects into the machine and do not attempt to bypass any guards or otherwise operate the machine in any manner other than that in which it is explicitly intended.

Note: The equipment is not for use with materials that can decompose or ignite below the maximum operating temperature of the machine. Hazards are materials that outgas hazardous substances and or ignite. (260°C/500°F).

Note: This equipment is not for use in an ATEX environment.

Note: Power down machine before disconnecting umbilical.

Equipment User Manual

Die Head Replacement

Caution: ensure the die heads are cooled to within 15 degrees °F of ambient temperature before proceeding with replacement.

Required Tools and Equipment
    2 open end or similar wrenches

1. Remove the 4 screws holding the heat shield.
2. Remove the heat shield.
3. Loosen the clamping nut and bolt located at the top and bottom of the heater housing.
4. Remove the existing die from the housing and replace it with alternate size die.
5. Tighten the clamping nut and bolt until the die is secure in the housing.
6. Reinstall the heat shield.

Parameter Settings

Cooling Air ON Toggle
- Place toggle in the up position for cooling air On, and toggle down for cooling air Off.

Cooling Air Flow Adjust
- Rotate the Cooling Flow valve counterclockwise to increase the cooling air flow, and clockwise to decrease the cooling air flow.

System Operations

CAUTION: Die housing and drawing dies will become hot during operation and, depending on temperature set-point, can cause severe skin burns if contact occurs.

1. Switch main power on.
2. Set die temperature on temperature controller by pressing the UP button once to see "SP1" displayed. Press the Enter button to display temperature. Use Left/Right arrows to set desired temperature. Once the desired temperature is set, press the Enter button to return to home.
3. Pass end of tubing through the necking die and grasp at opposite side.
4. Draw tubing through die at a speed that produces the desired tubing o.d.
5. To aid in obtaining tubing diameter, position the cooling air nozzle near the exit of the drawing die and switch cooling air "on" as tubing is drawn through the die.

Temperature Controllers (Omega Platinum Model)

Please note, the Omega temperature controllers have been auto tuned and are set for optimal performance. Contact Beahm Designs for further diagnostics and instructions.

PID Configuration (PRoG > PId.S)

◀ ▶	Navigate to the desired setting. Settings include the following: • ACtN – Action direction moves up or down to SP1. • A.to – Autotuning Timeout sets a maximum amount of time for Autotuning. • AUto – Initiates Autotuning • GAIN – Select the proportional, integral, and derivative factors for manual tuning. • %Lo – Low clamping limit for Pulse and Analog outputs • %HI – High clamping limit for Pulse and Analog outputs • AdPt – Fuzzy logic adaptive tuning
↵	Select the desired parameter.

Action Response (PRoG > PId > ACtN)

↵	Select the Direction (ACtN) parameter.
◀ ▶	Navigate to the desired setting. Settings include the following: • RVRS – "Reverse Action": Increase to SP1, such as heating (factory default) • dRCt – "Direct Action": Decrease to SP1, such as cooling • RVRS/dRCt – Increase or Decrease to SP1, such as heating/cooling
↵	Select the indicated setting.

Autotune Timeout (PRoG > PId > A.to)

↵	Select the Autotune Timeout (A.to) parameter.
◀ ▶	Set the amount of time before the Autotune process gives up and times out in Minutes and Seconds (MM.SS). Slowly responding systems should have a longer time-out setting.
↵	Select the indicated setting.

Autotune (PRoG > PId > TUNE)

↵	Select the Autotune (AUto) command. The unit displays StRt.
↵	Confirm Autotune activation. The unit attempts to optimize the P, I, and d settings by stimulating the system and measuring the response. If the A.to time out period expires before the Autotune operation can complete, the unit displays a failure message E007. If the Autotune operation completes successfully, the unit displays the message "doNE" and the Run mode is switched to IDLE.

The Autotune function will select the tuning algorithm depending on the stability of current process and the error difference between current process and the Control Setpoint (SP1). If the process is relatively stable (i.e: at room temperature), a bump test will be performed to determine the plant characteristics.

 If the process is hot, or if the process is within 10% of Control Setpoint, limit cycle oscillation will be performed with the tuning setpoint taken at the process value when the Autotune function is triggered. Autotuning may be performed as many times as needed or when the operating conditions (i.e: process load, or setpoint) have changed significantly. To obtain good tuning results, ensure the process is stable prior to triggering autotune function. The process is stable when it is at ambient temperature, or it is tracking Control Setpoint (SP1) in auto mode.

Adjusting Temperature on Controllers (Omega Platinum Model)

1. Press the right arrow button one time until "SP-1" is displayed. ▶
2. Press the enter button to access the temperature screen. ↵
3. Use the left and right arrow buttons to set desired temperature. ◀ ▶
4. Once the desired temperature is set, press the enter button to return to the main screen. ↵ Heaters will ramp to correct temperature.

Temperature Controller Layout and Description of Button Actions
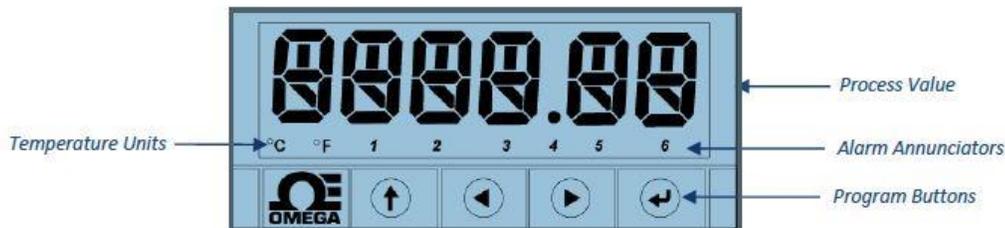
Figure 1. Controller Layout

Figure 2. Description of Button Actions

NOTE: For a more detailed look at the complete menu structure, please refer to the following pages. A full description of features can be found here: https://assets.omega.com/manuals/M5451.pdf.

Resetting the temperature controller

NOTE: Press '↑' to select the operator menu (Oper)
NOTE: See the following chart for the correct settings for the Beahm 43-B. Settings to change in RED.

1.   Initialization Mode Menu (INIt)
    a.   The following table maps the Initialization Mode (INIt) navigation:

Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
INPt	t.C.	k					Type K thermocouple
		J					Type J thermocouple
		t					Type T thermocouple
		E					Type E thermocouple
		N					Type N thermocouple
		R					Type R thermocouple
		S					Type S thermocouple
		b					Type B thermocouple
		C					Type C thermocouple
	Rtd	N.wIR	3 wl				3-wire RTD
			4 wl				4-wire RTD
			2 wl				2-wire RTD
		A.CRV	385.1				385 calibration curve, 100 Ω
			385.5				385 calibration curve, 500 Ω
			385.t				385 calibration curve, 1000 Ω
			392				392 calibration curve, 100 Ω
			391.6				391.6 calibration curve, 100 Ω
	tHRM	2.25k					2250 Ω thermistor
		5k					5000 Ω thermistor
		10k					10,000 Ω thermistor
	PRoC	4–20					Process input range: 4 to 20 mA
			Note: This Manual and Live Scaling submenu is the same for all PRoC ranges.				
			MANL	Rd.1	____		Low display reading
				IN.1	____		Manual input for Rd.1
				Rd.2	____		High display reading
				IN.2	____		Manual input for Rd.2
			LIVE	Rd.1	____		Low display reading
				IN.1	____		Live Rd.1 input, ENTER for current
				Rd.2	____		High display reading
				IN.2	____		Live Rd.2 input, ENTER for current
		0–24					Process input range: 0 to 24 mA
		+-10					Process input range: -10 to +10 V
			Note: +- 1.0 and +-0.1 support SNGL, dIFF and RtIO tYPE				
		+-1	tYPE	SNGL			Process input range: -1 to +1 V

Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
				dIFF			Differential between AIN+ and AIN-
				RtLO			Ratiometric between AIN+ and AIN-
		+-0.1					Process input range: -0.1 to +0.1 V
			Note: The +- 0.05 input supports dIFF and RtIO tYPE				
		+-.05	tYPE	dIFF			Differential between AIN+ and AIN-
				RtLO			Ratiometric between AIN+ and AIN-
							Process input range: -0.05 to +0.05 V
tARE	dSbL						Disable tARE feature
	ENbL						Enable tARE on oPER menu
	RMt						Enable tARE on oPER and Digital Input
LINR	N.PNt	_____					Specifies the number of points to use
			Note: The Manual / Live inputs repeat from 1..10, represented by n				
	MANL	Rd.n	____				Low display reading
		IN.n	____				Manual input for Rd.n
	LIVE	Rd.n	____				Low display reading
		IN.n	____				Live Rd.n input, ENTER for current
RdG	dEC.P	FFF.F					Reading format -999.9 to +999.9
		FFFF					Reading format -9999 to +9999
		FF.FF					Reading format -99.99 to +99.99
		F.FFF					Reading format -9.999 to +9.999
	°F°C	°C					Degrees Celsius annunciator
		°F					Degrees Fahrenheit annunciator
		NoNE					Turns off for non-temperature units
	d.RNd	_____					Display Rounding
	FLtR	8					Readings per displayed value: 8
		16					16
		32					32
		64					64
		128					128
		1					2
		2					3
		4					4
			Note: Four digit displays offer 2 annunciators, Six digit displays offer 6				
	ANN.n	ALM.1					Alarm 1 status mapped to "1"
		ALM.2					Alarm 2 status mapped to "1"
		oUt#					Output state selections by name
	NCLR	GRN					Default display color: Green
		REd					Red

Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
		AMbR					Amber
	bRGt	HIGH					High display brightness
		MEd					Medium display brightness
		Low					Low display brightness
ECtN	5 V						Excitation voltage: 5 V
	10 V						10 V
	12 V						12 V
	24 V						24 V
	0 V						Excitation off
CoMM	USb						Configure the USB port
		Note: This **PRot** submenu is the same for USB, Ethernet, and Serial ports.					
		PRot	oMEG	ModE	CMd		Waits for commands from other end
					CoNt	____	Transmit continuously every ###.# sec
				dAt.F	StAt	No	
						yES	Includes Alarm status bytes
					RdNG	yES	Includes process reading
						No	
					PEAk	No	
						yES	Includes highest process reading
					VALy	No	
						yES	Includes lowest process reading
					UNIt	No	
						yES	Send unit with value (F, C, V, mV, mA)
				_LF_	No		
					yES		Appends line feed after each send
				ECHo	yES		Retransmits received commands
					No		
				SEPR	_CR_		Carriage Return separator in **CoNt**
					SPCE		Space separator in **CoNt** Mode
			M.bUS	RtU			Standard Modbus protocol
				ASCI			Omega ASCII protocol
		AddR	____				USB requires Address
	EtHN	PRot					Ethernet port configuration
		AddR	____				Ethernet "Telnet" requires Address
	SER	PRot					Serial port configuration
		C.PAR	bUS.F	232C			Single device Serial Comm Mode
				485			Multiple devices Serial Comm Mode
			bAUd	19.2			Baud rate: 19,200 Bd

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Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
				9600			9,600 Bd
				4800			4,800 Bd
				2400			2,400 Bd
				1200			1,200 Bd
				57.6			57,600 Bd
				115.2			115,200 Bd
			PRty	odd			Odd parity check used
				EVEN			Even parity check used
				NoNE			No parity bit is used
				oFF			Parity bit is fixed as a zero
			dAtA	8bIt			8 bit data format
				7bIt			7 bit data format
			StoP	1bIt			1 stop bit
				2bIt			2 stop bits gives a "force 1" parity bit
		AddR	____				Address for 485, placeholder for 232
SFty	PwoN	RSM					RUN on power up if not previously faulted
		wAIt					Power on: oPER Mode, ENTER to run
		RUN					RUN's automatically on power up
	RUN.M	dSbL					ENTER in Stby, PAUS, StoP runs
		ENbL					ENTER in modes above displays RUN
	SP.LM	SP.Lo	____				Low Setpoint limit
		SP.HI	____				High Setpoint limit
	SEN.M						Sensor Monitor
		LPbk	dSbL				Loop break timeout disabled
			ENbL				Loop break timeout value (MM.SS)
		o.CRk	ENbl				Open Input circuit detection enabled
			dSbL				Open Input circuit detection disabled
		E.LAt	ENbl				Latch sensor error enabled
			dSbL				Latch sensor error disabled
	OUT.M						Output Monitor
		oUt1					oUt1 is replaced by output type
			o.bRk				Output break detection
				dSbL			Output break detection disabled
				ENbl	P.dEV	____	Output break process deviation
					P.tME	____	Output break time deviation
		oUt2					oUt2 is replaced by output type
		oUt3					oUt3 is replaced by output type
		E.LAt	ENbl				Latch output error enabled

Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
			dSbL				Latch output error disabled
t.CAL	NoNE						Manual temperature calibration
	1.PNt						Set offset, default = 0
	2.PNt	R.Lo					Set range low point, default = 0
		R.HI					Set range high point, default = 999.9
	ICE.P	ok?					Reset 32°F/0°C reference value
		dSbL					Clears the ICE.P offset value
SAVE	___						Download current settings to USB
LoAd	___						Upload settings from USB stick
VER.N	1.00.0						Displays firmware revision number
VER.U	ok?						ENTER downloads firmware update
F.dFt	ok?						ENTER resets to factory defaults
I.Pwd	No						No required password for INIt Mode
	yES	___					Set password for INIt Mode
P.Pwd	No						No password for PRoG Mode
	yES	___					Set password for PRoG Mode

2. Programming Mode Menu (PRoG)
   a. The following table maps the Programming Mode (PRoG) navigation:

Level 2	Level 3	Level 4	Level 5	Level 6	Notes
SP1	___				Process goal for PID, default goal for oN.oF
SP2	ASbo				Setpoint 2 value can track SP1, SP2 is an absolute value
	dEVI				SP2 is a deviation value
ALM.1	Note: This submenu is the same for all other Alarm configurations.				
	tyPE	oFF			ALM.1 is not used for display or outputs
		AboV			Alarm: process value above Alarm trigger
		bELo			Alarm: process value below Alarm trigger
		HI.Lo.			Alarm: process value outside Alarm triggers
		bANd			Alarm: process value between Alarm triggers
	Ab.dV	AbSo			Absolute Mode; use ALR.H and ALR.L as triggers
		d.SP1			Deviation Mode; triggers are deviations from SP1
		d.SP2			Deviation Mode; triggers are deviations from SP2
		CN.SP			Tracks the Ramp & Soak instantaneous setpoint
	ALR.H	___			Alarm high parameter for trigger calculations
	ALR.L	___			Alarm low parameter for trigger calculations
	A.CLR	REd			Red display when Alarm is active

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Level 2	Level 3	Level 4	Level 5	Level 6	Notes
		AMbR			Amber display when Alarm is active
		GRN			Green display when Alarm is active
		dEFt			Color does not change for Alarm
	HI.HI	oFF			High High / Low Low Alarm Mode turned off
		oN	____		Offset value for active High High / Low Low Mode
	LtCH	No			Alarm does not latch
		yES			Alarm latches until cleared via front panel
		botH			Alarm latches, cleared via front panel or digital input
		RMt			Alarm latches until cleared via digital input
	CtCL	N.o.			Output activated with Alarm
		N.C.			Output deactivated with Alarm
	A.P.oN	yES			Alarm active at power on
		No			Alarm inactive at power on
	dE.oN	____			Delay turning off Alarm (sec), default = 1.0
	dE.oF	____			Delay turning off Alarm (sec), default = 0.0
ALM.2					Alarm 2
oUt1					oUt1 is replaced by output type
	Note: This submenu is the same for all other outputs.				
	ModE	oFF			Output does nothing
		PId			PID Control Mode
			ACtN	RVRS	Reverse acting control (heating)
				dRCt	Direct acting control (cooling)
				RV.DR	Reverse/Direct acting control (heating/cooling)
		PId.2			PID 2 Control Mode
			ACtN	RVRS	Reverse acting control (heating)
				dRCt	Direct acting control (cooling)
				RV.DR	Reverse/Direct acting control (heating/cooling)
		oN.oF	ACtN	RVRS	Off when > SP1, on when < SP1
				dRCt	Off when < SP1, on when > SP1
			dEAd	____	Deadband value, default = 5
			S.PNt	SP1	Either Setpoint can be used of on/off, default is SP1
				SP2	Specifying SP2 allows two outputs to be set for heat/cool
		ALM.1			Output is an Alarm using ALM.1 configuration
		ALM.2			Output is an Alarm using ALM.2 configuration
		RtRN	Rd1	____	Process value for oUt1
			oUt1	____	Output value for Rd1
			Rd2	____	Process value for oUt2
			oUt2	____	Output value for Rd2

Level 2	Level 3	Level 4	Level 5	Level 6	Notes
		RE.oN			Activate during Ramp events
		SE.oN			Activate during Soak events
		SEN.E			Activate if any sensor error is detected
		OPL.E			Activate if any output is open loop
	CyCL	____			PWM pulse width in seconds
	RNGE	0-10			Analog Output Range: 0–10 Volts
		0-5			0–5 Volts
		0-20			0–20 mA
		4-20			4–20 mA
		0-24			0–24 mA
oUt2					oUt2 is replaced by output type
oUt3					oUt3 is replaced by output type (1/8 DIN can have up to 6)
Pid	ACtN	RVRS			Increase to SP1 (i.e., heating)
		dRCt			Decrease to SP1 (i.e., cooling)
		RV.DR			Increase or Decrease to SP1 (i.e., heating/cooling)
	A.to	____			Set timeout time for autotune
	tUNE	StRt			Initiates autotune after StRt confirmation
	GAIN	_P_	____		Manual Proportional Band setting
		_I_	____		Manual Integral Factor setting
		_d_	____		Manual Derivative Factor setting
	rCg	____			Relative Cool Gain (heating/cooling mode)
	oFst	____			Control Offset
	dEAd	____			Control Dead band/Overlap band (in process unit)
	%Lo	____			Low clamping limit for Pulse, Analog Outputs
	%HI	____			High clamping limit for Pulse, Analog Outputs
	AdPt	ENbL			Enable fuzzy logic adaptive tuning
		dSbL			Disable fuzzy logic adaptive tuning
Pid.2	Note: This menu is the same for PID menu.				
RM.SP	oFF				Use SP1, not remote Setpoint
	oN	4–20			Remote analog Input sets SP1; range: 4–20 mA
			Note: This submenu is the same for all RM.SP ranges.		
			RS.Lo	____	Min Setpoint for scaled range
			IN.Lo	____	Input value for RS.Lo
			RS.HI	____	Max Setpoint for scaled range
			IN.HI	____	Input value for RS.HI
		0–24			0–24 mA
		0–10			0–10 V
		0–1			0–1 V

Level 2	Level 3	Level 4	Level 5	Level 6	Notes
M.RMP	R.CtL	No			Multi-Ramp/Soak Mode off
		yES			Multi-Ramp/Soak Mode on
		RMt			**M.RMP** on, start with digital input
	S.PRG	____			Select program (number for **M.RMP** program), options 1–99
	M.tRk	RAMP			Guaranteed Ramp: soak SP must be reached in ramp time
		SoAk			Guaranteed Soak: soak time always preserved
		CYCL			Guaranteed Cycle: ramp can extend but cycle time can't
					Note: tIM.F does not appear for 6 digit display that use a HH:MM:SS format
	tIM.F	MM:SS			"Minutes : Seconds" default time format for R/S programs
		HH:MM			"Hours : Minutes" default time format for R/S programs
	E.ACt	StOP			Stop running at the end of the program
		HOLd			Continue to hold at the last soak setpoint at program end
		LINk	____		Start the specified ramp & soak program at program end
	N.SEG	____			1 to 8 Ramp/Soak segments (8 each, 16 total)
	S.SEG	____			Select segment number to edit, entry replaces # below
			MRt.#	____	Time for Ramp number, default = 10
			MRE.#	oFF	Ramp events on for this segment
				oN	Ramp events off for this segment
			MSP.#	____	Setpoint value for Soak number
			MSt.#	____	Time for Soak number, default = 10
			MSE.#	oFF	Soak events off for this segment
				oN	Soak events on for this segment

3. Operating Mode Menu (oPER)
   a. The following table maps the Operating Mode (oPER) navigation:

Level 2	Level 3	Level 4	Notes
RUN			Normal Run Mode, process value displayed, **SP1** in optional secondary display
SP1	____		Shortcut to change Setpoint 1, current Setpoint 1 value in main display
SP2	____		Shortcut to change Setpoint 2, current Setpoint 2 value in main display
MANL	M.CNt	____	Manual Mode, the RIGHT and LEFT buttons control output, displays **M##.#**
	M.INP	____	Manual Mode, the RIGHT and LEFT buttons simulate the input for testing
PAUS			Pause and hold at current process value, display flashes
StoP			Stop controlling, turn off outputs, process value rotating flash, Alarms remain
L.RSt			Clears any latched Alarms; Alarms menu also allows digital input reset
VALy			Displays the lowest input reading since the VALy was last cleared
PEAk			Displays the highest input reading since the PEAk was last cleared

Level 2	Level 3	Level 4	Notes
Stby			Standby Mode, outputs, and Alarm conditions disabled, displays Stby
tARE			TARE option - only available if enabled in INPt

Changing Temperature Units on the Omega Temperature Controller

1. Press the up button   until "oPER" appears on the screen.

2. Press the right arrow   until "1 NI t" appears on the screen. Press enter.

3. Press the right arrow   until "RdG" appears on the screen. Press enter.

4. "dEC.P" should be on screen. Press right arrow   to show "**°F °C**" on the screen. Press enter.

5. Use arrows   to switch from °C to °F. Press enter.

6. Press the up arrow   to go back to the "1 NI t" screen. Press the left arrow   to go back to "oPER".   Press enter   to see "RUN" and press enter again   to return to normal operating status.

Maintenance

Caution: pinch point/crush hazard. Keep fingers, hands, and clothing clear of moving parts.
1. Use 99% isopropyl alcohol to wipe down the outside of the machine. Do not attempt to clean the inside of the machine. The machine should not be washed down.
2. Cleaning should be with a soft dry cloth only.

Warning
Note: Ensure the machine is unplugged for any servicing or maintenance work.
Note: Perform these steps ONLY when the machine is at room temperature.

Critical Spare Parts (Contact Beahm Designs for pricing)

P/N	Description
120V – 1153590-001 220V – 1157788-001	HEATRER CARTRIDGE
1143133-001	THERMOCOUPLE, K TYPE, 0.125 OD.SLDPRT
1161899-001	TEMPERATURE CONTROLLER
1155195-001	SOLID STATE RELAY
1114668-005	24VDC POWER SUPPLY

Table 1. Critical Spare Parts

Facility Requirements
1. Voltage: 120-240 VAC, 50/60 hz
2. Wattage: 10 amps (500 watts)
3. Compressed Air: 100-125 psi, clean dry compressed air

Warranty

Beahm Designs Inc. (BDI) products are backed by a 1-year warranty on parts and labor. Warranty is void for any product returned if BDI determines that:

   a. The asserted defect is not present,
   b. The asserted defect is attributed to misuse, improper installation, alteration (label removal and/or destruction, opening or removing external covers without authorization by Beahm Designs Inc.), mishandling and/or mishaps.
   c. The product was not sold to customer as new.

Return Material Authorization

Product may not be returned to Beahm Designs Inc. without first contacting BDI Aftermarket for a Return Material Authorization (RMA) number. If it is determined that the Product may be defective, you will be given an RMA number and instructions for Product return. End Users are required to include a copy of the RMA receipt inside the return box, in order to receive replacement product under the warranty. All unauthorized returns i.e., one for which an RMA number has not been issued, will be returned at the customers expense. To request an RMA, please contact us at 928-556-3109 or email info@machinesolutions.com

For additional information on Beahm Designs, Split Die Thermal Bonder, please visit http://machinesolutions.com/our-products/