# MACHINE SOLUTIONS INC.



USER MANUAL

**3E4HM** 

DESIGNS

BEAHM DESIGNS Balloon Bonder 420-B Model



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Table of Contents	
List of Tables	
List of Figures	3
Welcome	4
Overview	4
Contents	4
Installation	4
Safety	5
User Alerts	5
Installation	5
Controls and Features	6
Parameter Settings	7
Pressure Regulator Setting	7
Process Timer Setting	7
System Operation	7
Temperature Controllers (Omega Platinum Model)	8
PID Configuration (PRoG > PId.S)	8
Action Response (PRoG > PId > ACtN)	8
Autotune Timeout (PRoG > Pld > A.to)	8
Autotune (PRoG > Pld > TUNE)	9
Adjusting Temperature on Controllers (Omega Platinum Model)	9
Temperature Controller Layout and Description of Button Actions	9
Resetting the temperature controller	10
Changing Temperature Units on the Omega Temperature Controller	19
Maintenance	19
Exchanging Die Heads	20
System Specifications	20
Calibration	20
Critical Spare Parts	21
Diagnostics (Troubleshooting)	21
Facilities Requirements	22
Warranty	22

2



 List of Tables

 Table 1. Control and Display Functions
 6

 Table 5. System Specifications
 20

 Table 6. Critical Spare Parts
 21

 Table 7. Diagnostics (Troubleshooting)
 21

List of Figures	
Figure 1. 420-B Front Panel	6
Figure 2. Controller Layout	9
Figure 3. Description of Button Actions	



# Welcome

Machine Solutions, Inc. (MSI) would like to take this opportunity to thank you for purchasing your new 420-B Balloon Bonder machine. At MSI, we are dedicated to bringing innovative process development solutions to both medical device and nonmedical organizations. The MSI proprietary segmental technology has been successfully implemented in manufacturing clean rooms on five continents, and continues to expand – meeting, growing, and facilitating the abilities of device companies around the globe. MSI looks forward to helping your organization provide life-improving devices to your customers, today and tomorrow.

### **Overview**

Thermal Die Bonder with Axial Compression. This system is equipped with dual Pneumatic tubing grips, centerline adjustment, adjustable compression, and variable timed cooling. The 420B provides a low-cost quick tool alternative to RF die bonding. The seven-parameter operation is easy to set-up and use and simplifies system calibration and process validation. This system provides you with fast, highly repeatable bonds. It also allows you to perform highly precise bonds for demanding applications such as short balloon bonds and ultra smooth lap & butt welds. Adjustable clamp pressure varies compression force on joint. Ultra compact design provides you with greater workspace.

# Contents

Included with the system are the following contents:

- Axial Compression Thermal Die Bonder
- IEC Power Cord

# Installation

Note: See Maintenance section for facilities requirements

- 1. Place the system on a level, sturdy surface at an ergonomically viable height for the user.
- 2. Connect the electrical umbilical to the die base unit.
- 3. Connect the power cord to the main control unit.
- 4. Connect the air supply to the system and then to a clean, dry, and filtered compressed air source.



#### Safety

- Use of eye protection when working with compressed gases and heated materials is advised.
- The maximum observed Sound Pressure Level is below 70 dB(A).



Caution: high voltage. Remove power and use safety precautions when servicing.



Caution: hot surface. Contact may cause burn. Allow to cool before servicing.



Caution: pinch point. Keep hands and body parts clear while in operation.

# **User Alerts**

Do not use the equipment other than as prescribed. Examples: Do not attempt to sit on or climb on the equipment, do not place heavy objects or containers of liquid on the machine, do not to insert any foreign objects into the machine and do not attempt to bypass any guards or otherwise operate the machine in any manner other than that in which it is explicitly intended.

# Installation

Note: The equipment is not for use with materials that can decompose or ignite below the maximum operating temperature of the machine. Hazards are materials that outgas hazardous substances and or ignite. (260°C/500°F)

Note: This equipment is not for use in an ATEX environment.



# **Controls and Features**

Located on the front panel are the following controls and/or displays and their function.

Description	Function
Main power switch	Toggles system power and air on and off.
Start switch	Initiates process sequence.
Stop/Abort/Reset	Interrupts the process sequence and resets the system timer.
	Resets the system after power up and if E Stop is depressed
Front Die temperature	Controls the temperature of the front die head.
controller	
Rear Die temperature	Controls the temperature of the rear die head.
controller	
Axial Compression Delay	Controls compression delay time.
Timer	
Weld Duration Timer	Controls the duration that the die heads are closed and/or in
	contact with the product.
<b>Cool Duration Timer</b>	Controls the duration the cooling air flows.
E Stop	Disrupts power to heaters and internal components.

 Table 1. Control and Display Functions



Figure 1. 420-B Front Panel



### **Parameter Settings**

**Pressure Regulator Setting** 

• Rotate the regulator knob clockwise to increase air pressure, counterclockwise to decrease air pressure output to the die head actuation cylinder.

**Process Timer Setting** 

• Depress the upper half of the blue rocker buttons to increase time duration, depress the lower half of the blue rocker button to decrease the time duration. Depress the timer reset button to accept the new value.

# **System Operation**

Hot die jaws will become hot during operation and depending on temperature set-point, can cause <u>severe</u> skin burns if contact occurs.

- 1. Switch main power on.
- 2. Set the die temperature on EACH temperature controller.
- 3. Set heat timer to desired duration in seconds.
- 4. Set Axial Compression Delay Timer to desired duration in seconds.
- 5. Set Cool Timer to desired duration in seconds.
- 6. Adjust Die Head pressure.
- 7. Adjust Tubing Grip Pressure.
- 8. Position components to be bonded within thermal jaws.
- 9. Depress footswitch/push start button.
- 10. Remove components upon completion of cool duration.



#### Temperature Controllers (Omega Platinum Model)

Please note, the Omega temperature controllers have been auto tuned and are set for optimal performance. Contact Beahm Designs for further diagnostics and instructions.

PID Configuration (PRoG > PId.S)

	Navigate to the desired setting. Settings include the following:
	• Active – Action direction moves up or down to SP1.
	<ul> <li>A.to – Autotuning Timeout sets a maximum amount of time for</li> </ul>
	Autotuning.
	• AUto – Initiates Autotuning
	<ul> <li>GAIN – Select the proportional, integral, and derivative factors for manual</li> </ul>
	tuning.
	<ul> <li>%Lo – Low clamping limit for Pulse and Analog outputs</li> </ul>
	<ul> <li>%HI – High clamping limit for Pulse and Analog outputs</li> </ul>
	<ul> <li>AdPt – Fuzzy logic adaptive tuning</li> </ul>
Ļ	Select the desired parameter.

Action Response (PRoG > PId > ACtN)

Ļ	Select the Direction (ACtN) parameter.
	Navigate to the desired setting. Settings include the following:
	• RVRS – "Reverse Action": Increase to SP1, such as heating (factory default)
	<ul> <li>dRCt – "Direct Action": Decrease to SP1, such as cooling</li> </ul>
	<ul> <li>RVRS/dRCt – Increase or Decrease to SP1, such as heating/cooling</li> </ul>
Ļ	Select the indicated setting.

Autotune Timeout (PRoG > PId > A.to)

L	Select the Autotune Timeout (A.to) parameter.
	Set the amount of time before the Autotune process gives up and times out in Minutes and Seconds (MM.SS). Slowly responding systems should have a longer time-out setting.
L	Select the indicated setting.



#### Autotune (PRoG > PId > TUNE)

ſ	Select the Autotune (AUto) command. The unit displays StRt.
J	Confirm Autotune activation. The unit attempts to optimize the P, I, and d settings by stimulating the system and measuring the response. If the A.to time out period expires before the Autotune operation can complete, the unit displays a failure message E007. If the Autotune operation completes successfully, the unit displays the message "doNE" and the Run mode is switched to IDLE.

The Autotune function will select the tuning algorithm depending on the stability of current process and the error difference between current process and the Control Setpoint (SP1). If the process is relatively stable (i.e. at room temperature), a bump test will be performed to determine the plant characteristics.

If the process is hot, or if the process is within 10% of Control Setpoint, limit cycle oscillation will be performed with the tuning setpoint taken at the process value when the Autotune function is triggered. Autotuning may be performed as many times as needed or when the operating conditions (i.e. process load, or setpoint) have changed significantly. To obtain good tuning results, ensure the process is stable prior to triggering autotune function. The process is stable when it is at ambient temperature, or it is tracking Control Setpoint (SP1) in auto mode.

Adjusting Temperature on Controllers (Omega Platinum Model)

- 1. Press the right arrow button one time until "SP-1" is displayed.
- Press the enter button to access the temperature screen.
- 3. Use the left and right arrow buttons to set desired temperature.
- 4. Once the desired temperature is set, press the enter button to return to the main screen.Heaters pramp to correct temperature.

Temperature Controller Layout and Description of Button Actions



Figure 2. Controller Layout





The UP button moves up a level in the menu structure. Pressing and holding the UP button navigates to the top level of any menu (**oPER**, **PRoG**, or **INIt**). This can useful if you get lost in the menu structure.



The LEFT button moves across a set of menu choices at a given level (up in the Section 4 menu structure tables). When changing numerical settings, press the LEFT button to make the next digit (one digit to the left) active.



The RIGHT button across a set of menu choices at a given level (down in the Section 4 menu structure tables. The RIGHT button also scrolls numerical values up with overflow to 0 for the flashing digit selected.



The ENTER button selects a menu item and goes down a level, or it enters a numerical value or parameter choice.

Figure 3. Description of Button Actions

**NOTE:** For a more detailed look at the complete menu structure, please refer to the following pages. A full description of features can be found here: <u>https://assets.omega.com/manuals/M5451.pdf</u>.

#### Resetting the temperature controller

NOTE: Press ' $\uparrow$ ' to select the operator menu (Oper)

NOTE: See the following chart for the correct settings for the Beahm 420B. Settings to change in RED.



#### 1. Initialization Mode Menu (INIt)

a. The following table maps the Initialization Mode (INIt) navigation:

Level	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
(INPt)	t.C.	k					Type K thermocouple
-		J			-	-	Type J thermocouple
		t					Type T thermocouple
		E					Type E thermocouple
		N					Type N thermocouple
		R					Type R thermocouple
		S				Ĵ.	Type S thermocouple
		b					Type B thermocouple
		С					Type C thermocouple
	Rtd	N.wIR	3 wl			1	3-wire RTD
-			4 wl				4-wire RTD
-			2 wl			(	2-wire RTD
		A.CRV	385.1				385 calibration curve, 100 Ω
			385.5				385 calibration curve, 500 Ω
-			385.t			1	385 calibration curve, 1000 Ω
			392				392 calibration curve, 100 Ω
	_		391.6				391.6 calibration curve, 100 Ω
	tHRM	2.25k					2250 Ω thermistor
Ĩ.		5k				Î	5000 $\Omega$ thermistor
		10k					10,000 Ω thermistor
-	PRoC	4-20					Process input range: 4 to 20 mA
Ĩ.			Note: Th	nis Manua	al and Live	Scaling s	submenu is the same for all PRoC ranges.
-			MANL	Rd.1			Low display reading
-				IN.1			Manual input for Rd.1
				Rd.2			High display reading
				IN.2			Manual input for Rd.2
-		-	LIVE	Rd.1			Low display reading
				IN.1			Live Rd.1 input, ENTER for current
				Rd.2			High display reading
-				IN.2			Live Rd.2 input, ENTER for current
1		0-24					Process input range: 0 to 24 mA
		+-10					Process input range: -10 to +10 V
-			Note: +-	1.0 and +	-0.1 supp	ort SNGL	, dIFF and RtIO tYPE
		+-1	tYPE	SNGL			Process input range: -1 to +1 V

11



Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
				dIFF			Differential between AIN+ and AIN-
	1		7	RtLO			Ratiometric between AIN+ and AIN-
		+-0.1					Process input range: -0.1 to +0.1 V
	ř		Note: Th	ne +- 0.05	input sup	ports dIF	F and RtIO tYPE
		+05	tYPE	dIFF		1	Differential between AIN+ and AIN-
		1		RtLO			Ratiometric between AIN+ and AIN-
	· · · · · ·						Process input range: -0.05 to +0.05 V
tARE	dSbL	(			0	6	Disable tARE feature
	ENbL						Enable tARE on oPER menu
	RMt						Enable tARE on oPER and Digital Input
LINR	N.PNt	-			0	-0	Specifies the number of points to use
			Note: Th	ne Manua	l / Live in	puts repe	at from 110, represented by n
	MANL	Rd.n					Low display reading
.0-	-	IN.n				1	Manual input for Rd.n
	LIVE	Rd.n					Low display reading
		IN.n					Live Rd.n input, ENTER for current
RdG	dEC.P	FFF.F				2	Reading format -999.9 to +999.9
$\sim$	-	FFFF					Reading format -9999 to +9999
		FF.FF				1	Reading format -99.99 to +99.99
	-	F.FFF					Reading format -9.999 to +9.999
	(°F°C)	0					Degrees Celsius annunciator
0		٩F					Degrees Fahrenheit annunciator
		NoNE					Turns off for non-temperature units
	d.RNd	12000					Display Rounding
0	(FLtR)	(8)					Readings per displayed value: 8
		16					16
		32			1		32
		64				0	64
		128					128
1		1				1	2
0		2				0	3
		4					4
			Note: Fo	our digit d	isplays of	fer 2 ann	unciators, Six digit displays offer 6
	ANN.n	ALM.1					Alarm 1 status mapped to "1"
		ALM.2					Alarm 2 status mapped to "1"
		oUt#					Output state selections by name
Č.	NCLR	GRN				0	Default display color: Green
		REd					Red



Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
5		AMbR				1	Amber
0	bRGt	HIGH				2	High display brightness
		MEd					Medium display brightness
	1	Low					Low display brightness
ECtN	5 V						Excitation voltage: 5 V
	10 V						10 V
Č.	12 V						12 V
0	24 V						24 V
1.12	0 V						Excitation off
CoMM	USb						Configure the USB port
-		Note: Th	nis PRot su	ubmenu is	s the same	e for USB	, Ethernet, and Serial ports.
		PRot	oMEG	ModE	CMd		Waits for commands from other end
		1			CoNt		Transmit continuously every ###.# sec
0	1			dAt.F	StAt	No	]
						yES	Includes Alarm status bytes
1					RdNG	yES	Includes process reading
0	1					No	1
					PEAk	No	
0						yES	Includes highest process reading
					VALy	No	
	1					yES	Includes lowest process reading
-17 	1				UNIt	No	
						yES	Send unit with value (F, C, V, mV, mA)
	1			_LF_	No		
-0					yES		Appends line feed after each send
				ECHo	YES	0	Retransmits received commands
					No		
-0				SEPR	_CR_	1	Carriage Return separator in CoNt
					SPCE		Space separator in CoNt Mode
1			M.bUS	RtU			Standard Modbus protocol
0				ASCI			Omega ASCII protocol
		AddR					USB requires Address
2	EtHN	PRot					Ethernet port configuration
		AddR					Ethernet "Telnet" requires Address
	SER	PRot					Serial port configuration
		C.PAR	bUS.F	232C			Single device Serial Comm Mode
				485			Multiple devices Serial Comm Mode
	1		bAUd	19.2			Baud rate: 19,200 Bd



Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
			9	9600			9,600 Bd
				4800			4,800 Bd
				2400			2,400 Bd
	i i			1200			1,200 Bd
				57.6			57,600 Bd
				115.2			115,200 Bd
	1		PRty	odd			Odd parity check used
	l i			EVEN	8		Even parity check used
				NoNE			No parity bit is used
				oFF			Parity bit is fixed as a zero
			dAtA	8blt			8 bit data format
				7blt			7 bit data format
			StoP	1blt			1 stop bit
				2blt	1		2 stop bits gives a "force 1" parity bit
		AddR					Address for 485, placeholder for 232
SFty	PwoN	RSM					RUN on power up if not previously faulted
		wAlt					Power on: oPER Mode, ENTER to run
		RUN					RUN's automatically on power up
	RUN.M	dSbL					ENTER in Stby, PAUS, StoP runs
	1	ENbL					ENTER in modes above displays RUN
	SP.LM	SP.Lo					Low Setpoint limit
		SP.HI	<u></u>				High Setpoint limit
	SEN.M						Sensor Monitor
	1	LPbk	dSbL				Loop break timeout disabled
			ENbL				Loop break timeout value (MM.SS)
		o.CRk	ENbl				Open Input circuit detection enabled
			dSbL			1	Open Input circuit detection disabled
		E.LAt	ENbl			Î	Latch sensor error enabled
	ľ		dSbL				Latch sensor error disabled
	OUT.M						Output Monitor
		oUt1					oUt1 is replaced by output type
	1		o.bRk				Output break detection
				dSbL	1		Output break detection disabled
1				ENbl	P.dEV		Output break process deviation
	1		0		P.tME		Output break time deviation
		oUt2					oUt2 is replaced by output type
		oUt3					oUt3 is replaced by output type
i.		E.LAt	ENbl				Latch output error enabled



Level 2	Level 3	Level 4	Level 5	Level 6	Level 7	Level 8	Notes
			dSbL				Latch output error disabled
t.CAL	NoNE		-			6	Manual temperature calibration
	1.PNt						Set offset, default = 0
	2.PNt	R.Lo					Set range low point, default = 0
		R.HI	1			6	Set range high point, default = 999.9
	ICE.P	ok?					Reset 32°F/0°C reference value
		dSbL					Clears the ICE.P offset value
SAVE	1 <u>0 - 10</u>		i		0	C.	Download current settings to USB
LoAd							Upload settings from USB stick
VER.N	1.00.0		-				Displays firmware revision number
VER.U	ok?	3	1. I.		0	6	ENTER downloads firmware update
F.dFt	ok?						ENTER resets to factory defaults
I.Pwd	No						No required password for INIt Mode
	yES					·	Set password for INIt Mode
P.Pwd	No						No password for PRoG Mode
	yES						Set password for PRoG Mode

#### 2. Programming Mode Menu (PRoG)

#### a. The following table maps the Programming Mode (PRoG) navigation:

Level	Level 3	Level 4	Level 5	Level 6	Notes	
SP1					Process goal for PID, default goal for oN.oF	
SP2	ASbo				Setpoint 2 value can track SP1, SP2 is an absolute value	
	dEVI				SP2 is a deviation value	
ALM.1	Note: This submenu is the same for all other Alarm configurations.					
	tyPE	oFF			ALM.1 is not used for display or outputs	
		AboV			Alarm: process value above Alarm trigger	
		bELo			Alarm: process value below Alarm trigger	
		HI.Lo.			Alarm: process value outside Alarm triggers	
		bANd			Alarm: process value between Alarm triggers	
	Ab.dV	AbSo Absolute Mode; use ALR.H and ALR.L as triggers				
		d.SP1			Deviation Mode; triggers are deviations from SP1	
		d.SP2			Deviation Mode; triggers are deviations from SP2	
		CN.SP			Tracks the Ramp & Soak instantaneous setpoint	
	ALR.H				Alarm high parameter for trigger calculations	
	ALR.L				Alarm low parameter for trigger calculations	
	A.CLR	REd			Red display when Alarm is active	



Level 2	Level 3	Level 4	Level 5	Level 6	Notes	
		AMbR			Amber display when Alarm is active	
		GRN			Green display when Alarm is active	
		dEFt		1	Color does not change for Alarm	
	HI.HI	oFF			High High / Low Low Alarm Mode turned off	
		oN			Offset value for active High High / Low Low Mode	
	LtCH	No			Alarm does not latch	
		YES	İ		Alarm latches until cleared via front panel	
		botH			Alarm latches, cleared via front panel or digital input	
		RMt			Alarm latches until cleared via digital input	
	CtCL	N.o.			Output activated with Alarm	
		N.C.			Output deactivated with Alarm	
	A.P.oN	yES			Alarm active at power on	
		No			Alarm inactive at power on	
	dE.oN				Delay turning off Alarm (sec), default = 1.0	
	dE.oF	<u></u>			Delay turning off Alarm (sec), default = 0.0	
ALM.2					Alarm 2	
oUt1					oUt1 is replaced by output type	
and the	Note: This submenu is the same for all other outputs.					
	ModE	oFF			Output does nothing	
		PId			PID Control Mode	
i i	i i		ACtN	RVRS	Reverse acting control (heating)	
				dRCt	Direct acting control (cooling)	
				RV.DR	Reverse/Direct acting control (heating/cooling)	
		PId.2			PID 2 Control Mode	
			ACtN	RVRS	Reverse acting control (heating)	
				dRCt	Direct acting control (cooling)	
	i i			RV.DR	Reverse/Direct acting control (heating/cooling)	
		oN.oF	ACtN	RVRS	Off when > SP1, on when < SP1	
				dRCt	Off when < SP1, on when > SP1	
			dEAd		Deadband value, default = 5	
			S.PNt	SP1	Either Setpoint can be used of on/off, default is SP1	
				SP2	Specifying SP2 allows two outputs to be set for heat/cool	
		ALM.1			Output is an Alarm using ALM.1 configuration	
1		ALM.2		10	Output is an Alarm using ALM.2 configuration	
		RtRN	Rd1		Process value for oUt1	
			oUt1		Output value for Rd1	
l j			Rd2	12 <u>1 - 1</u> 2	Process value for oUt2	
			oUt2		Output value for Rd2	



Level 2	Level 3	Level 4	Level 5	Level 6	Notes
		RE.oN			Activate during Ramp events
1		SE.oN			Activate during Soak events
		SEN.E			Activate if any sensor error is detected
		OPL.E			Activate if any output is open loop
	CyCL	<u></u>	-		PWM pulse width in seconds
Í.	RNGE	0-10			Analog Output Range: 0–10 Volts
		0-5			0–5 Volts
	1	0-20			0–20 mA
[ ]		4-20			4–20 mA
		0-24			0–24 mA
oUt2	1				oUt2 is replaced by output type
oUt3					oUt3 is replaced by output type (1/8 DIN can have up to 6)
PId	ACtN	RVRS			Increase to SP1 (i.e., heating)
i i		dRCt	-		Decrease to SP1 (i.e., cooling)
		RV.DR			Increase or Decrease to SP1 (i.e., heating/cooling)
[]	A.to				Set timeout time for autotune
i i	tUNE	StRt			Initiates autotune after StRt confirmation
	GAIN	_P_			Manual Proportional Band setting
		_L_			Manual Integral Factor setting
	2	_d_	a <u> </u>		Manual Derivative Factor setting
	rCg				Relative Cool Gain (heating/cooling mode)
	oFst				Control Offset
	dEAd	<u></u>			Control Dead band/Overlap band (in process unit)
i i	%Lo	<u>- 221 - 7</u> 2			Low clamping limit for Pulse, Analog Outputs
l	%HI				High clamping limit for Pulse, Analog Outputs
	AdPt	ENbL			Enable fuzzy logic adaptive tuning
		dSbL			Disable fuzzy logic adaptive tuning
PId.2	Note: T	his menu	is the sa	ime fo <mark>r</mark> P	ID menu.
RM.SP	oFF				Use SP1, not remote Setpoint
j – D	oN	4-20			Remote analog Input sets SP1; range: 4–20 mA
ii	(		Note: T	his subm	enu is the same for all RM.SP ranges.
			RS.Lo		Min Setpoint for scaled range
Ĵ.			IN.Lo	10 <u>1</u>	Input value for RS.Lo
1			RS.HI		Max Setpoint for scaled range
			IN.HI		Input value for RS.HI
		0-24			0–24 mA
	()	0-10		-	0–10 V
		0-1			0–1 V

17



Level	Level	Level	Level	Level	Notes	
2	3	4	5	6		
M.RMP	R.CtL	No			Multi-Ramp/Soak Mode off	
		yES		10 - 21	Multi-Ramp/Soak Mode on	
		RMt			M.RMP on, start with digital input	
	S.PRG				Select program (number for M.RMP program), options 1–99	
	M.tRk	RAMP	8		Guaranteed Ramp: soak SP must be reached in ramp time	
		SoAk			Guaranteed Soak: soak time always preserved	
		CYCL			Guaranteed Cycle: ramp can extend but cycle time can't	
			Note: tl	ote: tIM.F does not appear for 6 digit display that use a HH:MM:SS format		
	tIM.F	MM:SS			"Minutes : Seconds" default time format for R/S programs	
		HH:MM	l		"Hours : Minutes" default time format for R/S programs	
	E.ACt	StOP	2	2: a	Stop running at the end of the program	
		HOLd			Continue to hold at the last soak setpoint at program end	
		LINk	s <del></del>		Start the specified ramp & soak program at program end	
	N.SEG		l l		1 to 8 Ramp/Soak segments (8 each, 16 total)	
	S.SEG		8		Select segment number to edit, entry replaces # below	
_			MRt.#		Time for Ramp number, default = 10	
			MRE.#	oFF	Ramp events on for this segment	
				oN	Ramp events off for this segment	
			MSP.#	<u></u>	Setpoint value for Soak number	
			MSt.#	1 <u>12 (</u> 1	Time for Soak number, default = 10	
			MSE.#	oFF	Soak events off for this segment	
			[	oN	Soak events on for this segment	

#### 3. Operating Mode Menu (oPER)

a. The following table maps the Operating Mode (oPER) navigation:

Level 2	Level 3	Level 4	Notes	
RUN			Normal Run Mode, process value displayed, SP1 in optional secondary display	
SP1			Shortcut to change Setpoint 1, current Setpoint 1 value in main display	
SP2	12 21		Shortcut to change Setpoint 2, current Setpoint 2 value in main display	
MANL	M.CNt		Manual Mode, the RIGHT and LEFT buttons control output, displays M##.#	
	M.INP	- <u></u> -	Manual Mode, the RIGHT and LEFT buttons simulate the input for testing	
PAUS			Pause and hold at current process value, display flashes	
StoP			Stop controlling, turn off outputs, process value rotating flash, Alarms remain	
L.RSt			Clears any latched Alarms; Alarms menu also allows digital input reset	
VALy			Displays the lowest input reading since the VALy was last cleared	
PEAk	0		Displays the highest input reading since the PEAk was last cleared	



Level 2	Level 3	Level 4	Notes	
Stby			Standby Mode, outputs, and Alarm conditions disabled, displays Stby	
tARE			TARE option - only available if enabled in INPt	

Changing Temperature Units on the Omega Temperature Controller

63 until "oPER" appears on the screen. 1. Press the up button 2. Press the right arrow until "1 NI t" appears on the screen. Press enter. 3 7 3. Press the right arrow until "RdG" appears on the screen. Press enter. enter. 💽 💽 to switch from °C to °F. Press enter. 🖉 5. Use arrows 6. Press the up arrow 🚯 to go back to the "1 NI t" screen. Press the left arrow 🔇 to go back to "oPER". Press enter to see "RUN" and press enter again to **(21)** return to normal operating status.

### Maintenance

A DANGER Pinch point.

Caution: pinch point/crush hazard. Keep fingers, hands, and clothing clear of moving parts.

- 1. Use 99% isopropyl alcohol to wipe down the outside of the machine. Do not attempt to clean the inside of the machine. Machine should not be washed down.
- 2. Cleaning should be with a soft dry cloth only.



#### Warning

Note: Ensure the machine is unplugged for any servicing or maintenance work. Note: Perform these steps ONLY when the machine is at room temperature.



#### Exchanging Die Heads

**Caution:** ensure that the die heads are cooled to within 15 degrees of ambient temperature before proceeding with replacement.

- Loosen the set screw located on the top of each die head and withdraw the thermocouple.
- Remove the four screws at the base of each die head.
- Position new die heads in place of removed die heads, install four screws at the base of each die head. Do not overtighten the screws.
- Install the thermocouple in the rear of each die head and gently tighten the set screw to hold them in place.

Description	Range	Resolution	Accuracy				
Temperature	Ambient-500°F	1.0 deg.	±.25% F.S.				
Controller							
Die Temperature	Ambient-500°F	N/A	±10°F				
Heat Duration	1-9999 seconds	1.0 sec	± .1 sec				
Cool Duration	1-9999 seconds	1.0 sec	± .1 sec				
Die Pressure	0-60 psi	2.0 psi	± 1.5% F.S.				
Table 2 System Specifications							

# **System Specifications**

**Table 2. System Specifications** 

# Calibration

#### **IMPORTANT NOTES:**

- A) It is recommended that calibration be performed by a certified service, preferably with the system in the location of use. Calibration procedures are the domain of these service providers.
- B) Calibration refers to the process of verifying that each of the systems' instruments that control a process parameter is within manufacturers' specification.
- C) Calibration DOES NOT refer to the process of measuring the temperature at the center of the tooling and "matching" the value to the temperature controller set point.
- D) The measured value at the tooling may not match the temperature controller set point and the.
  - 1. Calibrate the temperature controller annually.
  - 2. Calibrate the timers annually.
  - 3. Calibrate the pressure gauge annually.



# **Critical Spare Parts**

Part	Description
Number	
1153590-001	HEATER, CARTRIDGE, 120VAC, 1.5in, 100w (configuration specific)
1157788-001	HEATER, CARTRIDGE, 220VAC, 1.5IN, 100W (configuration specific)
1143133-001	THERMOCOUPLE, K TYPE, 0.125 OD
1153460-001	SOCKET TIMER
1143303-001	TIMER, DIGITAL, LT4H, 24VDC, COLOR LCD, 8 MODES
1161899-001	TEMP CONTROLLER
1143287-001	RELAY, 24VDC INTEGRATED
119106-001	RELAY, MODULE THIN, 24V, DIN RAIL N1PDT
1145619-001	RELAY, 24VDC, INTEGRATED, 4PDT
1343250-001	VALVE, 2-WAY 24 VCD, MAC
1330445-003	VALVE, 5-2, 24VDC, BODY PORTED

#### Table 3. Critical Spare Parts

# **Diagnostics (Troubleshooting)**

Issue	Possible Causes	Solution
Temperature not stable	Die heads replaced.	Auto-tune
	Thermocouple loose	Re-install thermocouple(s)
Die heads do not close	Air pressure too low	Increase air pressure
	Timer set to "0"	Increase Heat Duration
	Valve defective	Replace valve
Die head(s) do not heat	Loose connection to main control unit.	Verify secure connections
	Defective Temperature controller.	Replace temperature controller.
.Err code in display	Temperature controller software	Replace temperature controller.
	failure.	
System will not power on.	Emergency stop switch	Rotate switch knob to engage.
	depressed.	Verify installation.
	IEC power cord not fully	
	connected.	

Table 4. Diagnostics (Troubleshooting)

21



### **Facilities Requirements**

Wattage:

- Voltage: 120/240 VAC (depends on configuration) 50/60 Hz.
  - 500 max.
- Compressed Air:

500 max. 60-125 psi, 0.5 SCFM, filtered 50 micron or greater, oil and water free.

# Warranty

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Beahm Designs Inc. (BDI) products are backed by a 1 year warranty on parts and labor. Warranty is void for any Product returned if BDI determines that:

- 1. The asserted defect is not present,
- 2. The asserted defect is attributable to misuse, improper installation, alteration (including removing or obliterating labels and opening or removing external covers (unless authorized to do so by Beahm Designs), accident or mishandling while in the possession of someone other than Beahm Designs, Inc.
- 3. The Product was not sold to you as new.

#### **Return Material Authorization (RMA)**

No Product may be returned directly to BDI without first contacting BDI for a Return Material Authorization ("RMA") number. If it is determined that the Product may be defective, you will be given an RMA number and instructions for Product return. End Users are required to include a copy of the RMA receipt inside the return box to receive replacement product under warranty. An unauthorized return, i.e., one for which an RMA number has not been issued, will be returned to you at your expense. To request an RMA, please call 928-556-3109 or email service@machinesolutions.com

For additional information on Beahm Designs, Balloon Bonder, please visit <a href="http://machinesolutions.com/our-products/">http://machinesolutions.com/our-products/</a>